## Computational Physics

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## Series Integration

review from last lecture
trapezoidal rule


$$
\int_{x_{a}}^{x_{b}} f(x) d x=I_{N}+O\left(w^{2}\right)
$$

$$
I_{N}=\frac{w}{2} *\left(f\left(x_{a}\right)+f\left(x_{b}\right)+2 \sum_{k=1}^{N-1} f\left(x_{a}+k w\right)\right)
$$

$$
\epsilon_{2}=\frac{1}{3}\left|I_{N_{2}}-I_{N_{1}}\right|
$$

Simpson's rule

$$
\int_{x_{a}}^{x_{b}} f(x) d x=I_{N}+O\left(w^{4}\right)
$$

$$
\begin{gathered}
I_{N}=\frac{w}{6}\left[f\left(x_{a}\right)+f\left(x_{b}\right)+2 \sum_{k=1}^{N-1} f\left(x_{a}+k w\right)\right. \\
\left.+4 \sum_{k=0}^{N-1} f\left(x_{a}+w(k+1 / 2)\right)\right] \\
\epsilon_{2}=\frac{1}{15}\left|I_{N_{2}}-I_{N_{1}}\right| \\
\text { error on } 2^{\text {nd }} \text { integration }
\end{gathered}
$$

## Adaptive Integration

Integration with just enough steps, $N$, to achieve the accuracy we want

- Decide on the integration accuracy
- Evaluate the integral with a small number of steps $\mathrm{N}_{1}$
- Then double the number $\mathrm{N}_{2}=2 \mathrm{~N}_{1}$, \& evaluate integral again
- Calculate the error on $\mathrm{I}_{2}$
- use

$$
\epsilon_{2}=\frac{1}{3}\left|I_{2}-I_{1}\right|_{\text {rrapecodial }} \text { or } \epsilon_{2}=\frac{\mathbf{1}}{\mathbf{1 5}}\left|I_{2}-\boldsymbol{I}_{1}\right|_{\text {Simpson }}
$$

- If error is to within accuracy then we are finished, otherwise repeat doubling of integration steps until desired accuracy is reached


## Adaptive Integration

## Doubling the number of integration steps with half the calculations


doubling effectively adds an additional set of points halfway between the previous points

$$
I_{N}=w\left(\frac{1}{2} f\left(x_{a}\right)+\frac{1}{2} f\left(x_{b}\right)+\sum_{k=1}^{N-1}\left[f\left(x_{a}+k w\right)\right]\right)
$$

## Adaptive Integration

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$$

adaptive trapezoidal rule integration (extra points are the odd points)
$I_{2}=\frac{1}{2} I_{1}+w_{2} * \sum_{\substack{k o d d \\ 1 \ldots N_{2}-1}} f\left(x_{a}+k w_{2}\right)$

$$
N_{2}=2 \mathrm{~N}_{1} \quad w_{2}=\frac{w_{1}}{2} \quad \epsilon_{2}=\frac{1}{3}\left|I_{2}-I_{1}\right|
$$

## Adaptive Integration

## Doubling the number of integration steps with half the calculations

| $1 / 2$ | 1 | 1 | 1 | $1 / 2$ |
| :---: | :---: | :---: | :---: | :---: |
| 1 | 1 | 1 | 1 | 1 |

doubling effectively adds an additional set of points halfway between the previous points


$$
I_{N}=\frac{w}{6}\left[f\left(x_{a}\right)+f\left(x_{b}\right)+2 \sum_{k=1}^{N-1} f\left(x_{a}+k w\right)+4 \sum_{k=0}^{N-1} f\left(x_{a}+w(k+1 / 2)\right)\right]
$$

$$
I_{N}=w\left(\frac{1}{2} f\left(x_{a}\right)+\frac{1}{2} f\left(x_{b}\right)+\sum_{k=1}^{N-1}\left[f\left(x_{a}+k w\right)\right]\right)
$$

adaptive trapezoidal rule integration
(extra points are the odd points)
$I_{2}=\frac{1}{2} I_{1}+w_{2} * \sum_{\substack{k o d d \\ 1 \ldots N_{2}-1}} f\left(x_{a}+k w_{2}\right)$
$\boldsymbol{N}_{2}=\mathbf{2} \mathrm{N}_{1} \quad \boldsymbol{w}_{2}=\frac{\boldsymbol{w}_{1}}{\mathbf{2}} \quad \epsilon_{2}=\frac{\mathbf{1}}{\mathbf{3}}\left|I_{2}-\boldsymbol{I}_{1}\right|$
adaptive Simpson's rule integration (extra points are the new mid points minus odd endpoint point values)

$$
\begin{aligned}
& I_{2}=\frac{1}{2} I_{1}-\frac{1}{3} w_{2} \sum_{\substack{k o d d \\
k=1}}^{N_{2}-1} f\left(x_{a}+w_{2} k\right) \\
& \quad+\frac{2}{3} w_{2} \sum_{k=0}^{N_{2}-1} f\left(x_{a}+w_{2}(k+1 / 2)\right) \\
& \boldsymbol{N}_{\mathbf{2}}=\mathbf{2 N}_{\mathbf{1}} \quad \boldsymbol{w}_{\mathbf{2}}=\frac{\boldsymbol{w}_{\mathbf{1}}}{\mathbf{2}} \quad \epsilon_{2}=\frac{\mathbf{1}}{\mathbf{1 5}}\left|\boldsymbol{I}_{2}-\boldsymbol{I}_{\mathbf{1}}\right|
\end{aligned}
$$

## Integrals over infinite ranges

$$
\int_{0}^{\infty} f(x) d x
$$

Solve by changing variables:

$$
z=\frac{x}{1+x} \rightarrow x=\frac{z}{(1-z)} \& d x=\frac{d z}{(1-z)^{2}}
$$

$$
\int_{0}^{\infty} f(x) d x=\int_{0}^{1} \frac{1}{(1-z)^{2}} f\left|\frac{z}{1-z}\right| d z
$$

## Integrals over infinite ranges

$$
\int_{0}^{\infty} f(x) d x
$$

solution is to change variables: $\quad z=\frac{x}{1+x} \rightarrow x=\frac{z}{(1-z)} \& d x=\frac{d z}{(1-z)^{2}}$

$$
\int_{0}^{\infty} f(x) d x=\int_{0}^{1} \frac{1}{(1-z)^{2}} f\left|\frac{z}{1-z}\right| d z
$$

We can make two changes of variables: $y=x-a \& z=y /(1+y)$
to calculate:

$$
\int_{a}^{\infty} f(x) d x=\int_{0}^{1} \frac{1}{(1-z)^{2}} f\left|\frac{z}{1-z}+a\right| d z
$$

## Multi-Dimensional Integration "Divide and Conquer"

$$
\begin{array}{ll}
\int_{x_{a}}^{x_{b}} \int_{y_{a}}^{y_{b}} f(x, y) d y d x & f(x)=\int_{y_{a}}^{y_{b}} f(x, y) d y \\
\int_{x_{a}}^{x_{b}} f(x) d x & \text { Solve by Series Integration }
\end{array}
$$

> Trapezoidal
> Simpson's Rule

For N points in each integral calculation there are $\mathrm{N}^{2}$ calculations

## Multi-Dimensional Integration

Example: Atomic Physics

$$
I=\int_{0}^{1} d x_{1} \int_{0}^{1} d x_{2} \ldots \int_{0}^{1} d x_{12} f\left(x_{1}, x_{2,} \ldots x_{12}\right)
$$


${ }^{4} B e$
3 Dimension/electron * 4 electrons $=12$ Dimensions

For 100 steps in each integration there are $100^{12}=10^{24}$ calculations

Assuming 1 Giga evaluations/sec It would take over $10^{7}$ years!!!!

## Monte Carlo Integration

Using Random Numbers to Solve Integrals

Monte Carlo methods provide an alternative method of calculating an integral.

## Random Numbers

## Pseudo-Random Numbers

The numbers are pseudo-random in the sense that they are generated deterministically from a seed number, but are distributed in what has statistical similarities to random fashion.

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## Python modules for generating random numbers:

- import random:
- a smaller set of functions for random numbers
- import numpy.random:
- a more complete set of utilities with many generating functions along with array manipulation capabilities


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## Python modules for generating random numbers:

- import random:
- a smaller set of functions for random numbers
- import numpy.random:
- a more complete set of utilities with many generating functions along with array manipulation capabilities

Numpy.random and random modules uses a Mersenne Twister algorithm to generate pseudorandom numbers which has become the generator of choice for serious physics calculations.

## NumPy's random module

import numpy as np
>>> np.random.seed(136)
The seed is an integer value. Any program that starts with the same seed will generate exactly the same sequence of random numbers each time it is run. This is useful for debugging programs but otherwise not needed as the seed is uniquely set each time the program executes.

Note: one could also import via:
import numpy.random as rnd
>>> rnd.seed(136)

## NumPy's random module

Generate random integers in the range [min, max) >>> np.random.randint(5,10) 8

Generates a single random number in $[0.0,1.0)$
>>> np.random.random()
0.70110427435769551

Generate an array of random numbers in the interval [0.0, 1.0)
>>> np. random. rand (1)
array ([ 0.73549029])
>>> np. random. rand (5)
array ([ 0.6652181, 0.58861746, 0.8514131, 0.68607923, 0.8785746 ])
>>> np. random. rand $(2,3)$
$\operatorname{array}\left(\left[\begin{array}{llll}{[ } & 0.81698429, & 0.632073, & 0.10512043], \\ {[ } & 0.88226248, & 0.47654622, & 0.45082853\end{array}\right]\right)$

## NumPy's random module

hpc-login\% pydoc numpy.random
-••
DESCRIPTION


```
Random Number Generation
```



```
...
```



```
Univariate distributions
==================================================================================
beta Beta distribution over '`[0, 1]``.
binomial
chisquare
exponential
f
gamma
geometric
gumbel
hypergeometric
laplace
logistic
lognormal
logseries
negative_binomial
noncentrāl_chisquare
noncentral_f
normal
pareto
poisson
Binomial distribution.
:math:`\chi^2` distribution.
Exponential distribution.
F (Fisher-Snedecor) distribution.
Gamma distribution.
Geometric distribution.
Gumbel distribution.
Hypergeometric distribution.
Laplace distribution.
Logistic distribution.
Log-normal distribution.
Logarithmic series distribution.
Negative binomial distribution.
Non-central chi-square distribution.
Non-central F distribution.
Normal / Gaussian distribution.
Pareto distribution.
Poisson distribution.
```


## Generating random distributions

## hpc-login-24 \% pydoc numpy.random.normal

Help on built-in function normal in numpy.random:
numpy.random.normal $=$ normal(...)
normal (loc=0.0, scale=1.0, size=None)
Draw random samples from a normal (Gaussian) distribution.
The probability density function of the normal distribution, first derived by De Moivre and 200 years later by both Gauss and Laplace independently [2]_, is often called the bell curve because of its characteristic shape (see the example below).

The normal distributions occurs often in nature. For example, it describes the commonly occurring distribution of samples influenced by a large number of tiny, random disturbances, each with its own unique distribution [2]_.

## Parameters

loc : float or array_like of floats
Mean ("centre") of the distribution.
scale : float or array_like of floats
Standard deviation (spread or "width") of the distribution.
size : int or tuple of ints, optional
Output shape. If the given shape is, e.g., $(m, n, k) \cdots$, then
" $m$ * $n$ * $k$ "" samples are drawn. If size is ""None" (default),
a single value is returned if ""loc" and ""scale" are both scalars. Otherwise, "'np.broadcast(loc, scale).size" samples are drawn.
import numpy as np
>>> import matplotlib.pyplot as plt
$\ggg$
>>> plt.hist(numpy.random.normal(size=10000), bins=numpy.linspace(-3, 3,100 ))
>>> plt.show()

## Monte Carlo Integration

- Two of the most common ways to employ Monte Carlo techniques are
- Monte Carlo Sampling method
- Monte Carlo Mean-Value method


## Monte Carlo Sampling Method

## "random marks"

Box off the region of integration

- calculate the area of the box
- Randomly place points in the box
- Count \# of points in the box vs \# under the function
- Area $_{f(x)}=$ Area $_{\text {box }} * N_{f(x)} / N_{\text {box }}$

$$
\begin{aligned}
\mathrm{N}_{\mathrm{f}(\mathrm{x})} & =\# \bullet \\
\mathrm{~N}_{\mathrm{box}} & =\# \bullet+\# \bullet
\end{aligned}
$$



## Monte Carlo Mean-Value Method

"The Work Horse"
Integration using the Monte Carlo method is done by averaging the value of the function at randomly selected points within the integration interval

$$
I=\int_{a}^{b} d x f(x)=(b-a)\langle f\rangle
$$



$$
\langle f\rangle \simeq \frac{1}{N} \sum_{i=0}^{N} f\left(x_{i}\right)
$$

Statistical Error

$$
\delta I \sim \sigma_{\bar{f}}
$$

## Example: MC integration

```
import numpy.random as rnd
```

nUnder $=0$
for _ in range(nPoints):
$\mathrm{x}=\mathrm{xMin}+(x M a x-x M i n) * r n d . r a n d o m()$
fRand $=\mathrm{fMin}+(\mathrm{fMax}-\mathrm{fMin}) *$ rnd.random()
if fRand $<\mathbf{f}(\mathbf{x})$ :
nUnder += 1
print("Integration by Samples = ", \}
fMax*(xMax - xMin) * nUnder/nPoints)
import numpy.random as rnd
sum $=0$
for _ in range(nPoints):
$\mathrm{x}=\mathrm{xMin}+(\mathrm{xMax}-\mathrm{xMin})$ *rnd.random()
sum $+=\mathbf{f}(\mathbf{x})$
print("Integration by Mean-Value $=$ ", \}
(xMax - xMin) * sum/nPoints )


## Multi-Dimensional Monte Carlo

- Easy to generalize mean-value integration to many dimensions

$$
I=\int_{a}^{b} d x \int_{c}^{d} d y f(x, y) \simeq(b-a)(d-c) * \frac{1}{N} \sum_{i}^{N} f\left(x_{i}, y_{i}\right)
$$

## Multi-Dimensional Monte Carlo

- Easy to generalize mean-value integration to many dimensions

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I=\int_{a}^{b} d x \int_{c}^{d} d y f(x, y) \simeq(b-a)(d-c) * \frac{1}{N} \sum_{i}^{N} f\left(x_{i}, y_{i}\right)
$$

import numpy.random as rnd

```
def integrateMC(func, dim, limit, \(N=100)\) :
    I,sum \(=1 / \mathrm{N}, 0\)
    for \(n\) in range(dim):
        I *= (limit[n][1] - limit[n][0])
    for \(k\) in range(N):
        \(\mathrm{x}=\mathrm{l}]\)
        for \(n\) in range(dim):
            \(\mathrm{x}+=\) [limit[n][0] + (limit[n][1] - limit[n][0])*rnd.random()]
        sum \(+=\) func \((x)\)
    return I*sum
```

multi-dimensional Monte Carlo integration implementation
def $f(x)$ :
return $n p . \sin (x[0] * x[1] * * 2) \sim$ integrand function $f(x, y)=\sin (x y)$
integrand function $f(x, y)=\sin \left(x y^{2}\right)$
dim,limit $=2,[[0, n p . p i],[0, n p . p i]]$
print(integrateMC(f, dim, limit))
main part of program

## Multi-Dimensional Integration via MC mean value

Example: Atomic Physics

$$
\left.\begin{array}{l}
I=\int_{0}^{1} d x_{1} \int_{0}^{1} d x_{2} \ldots \int_{0}^{1} d x_{12} f\left(x_{1}, x_{2}, \ldots x_{12}\right) \\
3 \text { Dimension/electron } * 4 \text { electrons }=12 \text { Dimensions } \\
\quad \simeq(1-0)^{12} * \frac{1}{N} \sum_{i}^{N} f\left(x_{1,}{ }^{i} \quad x_{2}, \quad \ldots\right. \\
{ }^{i}
\end{array} x_{12}{ }^{i}\right) \text {. }
$$


${ }^{4} B e$

For $\mathrm{N}=10^{6}$ random points in the MC integration there are $\sim 10^{6}$ calculations
Assuming 1 Giga evaluations/sec It would take $\sim 10^{-3} \mathrm{sec}$

## Monte Carlo Error

## - Monte Carlo error is Statistical

- Error decreases as $1 / \sqrt{N}$

Mean-Value Integration is an ordinary statistical mean

$$
\bar{x}=\frac{1}{N} \sum_{\mathrm{i}=1}^{N} x_{i}
$$

The error on the mean is the standard deviation of the mean (SDOM)

$$
\sigma_{\bar{x}}=\frac{\sigma_{x}}{\sqrt{N}}
$$

With the standard deviation $\sigma_{\xi}$ defined as usual

$$
\sigma_{x}=\sqrt{\frac{1}{N-1} \sum\left(x_{i}-x_{b}\right)^{2}}
$$

Note: $\sum\left[\left(x_{i}-\bar{x}\right)^{2}\right]=\left[\sum\left(x_{i}\right)^{2}\right]-N \bar{x}^{2}$ is very useful in computing SDOM!

## Monte Carlo Error



See python code at
http://hadron.physics.fsu.edu/~eugenio/comphy/examples/mcint.py

Let's get working on \#5


