

# Computational Physics

## More on Objects in Python

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<http://hadron.physics.fsu.edu/~eugenio/comphy>

# Recall

## Class defines an Object

```
# Defining a class
class ClassName:
    """ Doc string information
        """
    [statement 1]
    [statement 2]
    [statement 3]
    [etc.]
```

An **object** is an **instance** of a **class** just like a **float variable** is an **instance** of a **float data type**

```
myClass = ClassName("Physics")
goldenRation = float("1.618")
```

# Simple Example: A Circle

## Class Definition of Simple Circle

```
class Circle:
    def __init__(self, radius=1):
        self.radius = radius

    def area(self):
        return np.pi*self.radius**2

    def circumference(self):
        return 2*np.pi*self.radius

    def __add__(self, other):
        return Circle(self.radius + other.radius)

    def print(self):
        print( "Hello, I am a circle" )
        print( "my radius is",self.radius )
        print( "My area is", self.area() )
        print( "My circumference is", self.circumference() )
```

# Simulating Floating Garbage

```
class Garbage():
    """
    Garbage is an object which simulates the random floating of trash in
    a current-less ocean
    """
    def __init__(self, x=0, y=0):
        """ Each piece of garbage has an (x,y) position. """
        self.x = x
        self.y = y

    def move(self, x_increment=0, y_increment=0):
        """
        Move the garbage according to the parameters given.
        Default behavior is to stay put
        """
        self.x = self.x + x_increment
        self.y = self.y + y_increment

    def get_distance(self, other):
        """
        Calculates the distance from this piece to another piece,
        and returns that value.
        """
        distance = np.sqrt( (self.x - other.x)**2 + (self.y - other.y )**2 )
        return distance
```

# Floating Garbage

```
class Garbage():  
  
    ...  
  
    def float(self):  
        """  
        random floating movement: moves one unit East, North, West, South,  
        or stays put  
        """  
        direction = np.random.randint(5)  
        dx, dy = 0, 0 # default is not to move in any direction  
  
        if direction == 1:           # move East  
            dx = 1  
        elif direction == 2:        # move North  
            dy = 1  
        elif direction == 3:        # move West  
            dx = -1  
        elif direction == 4:        # move South  
            dy = -1  
  
        self.move(dx, dy)
```

# Floating Garbage

```
#
# main
#

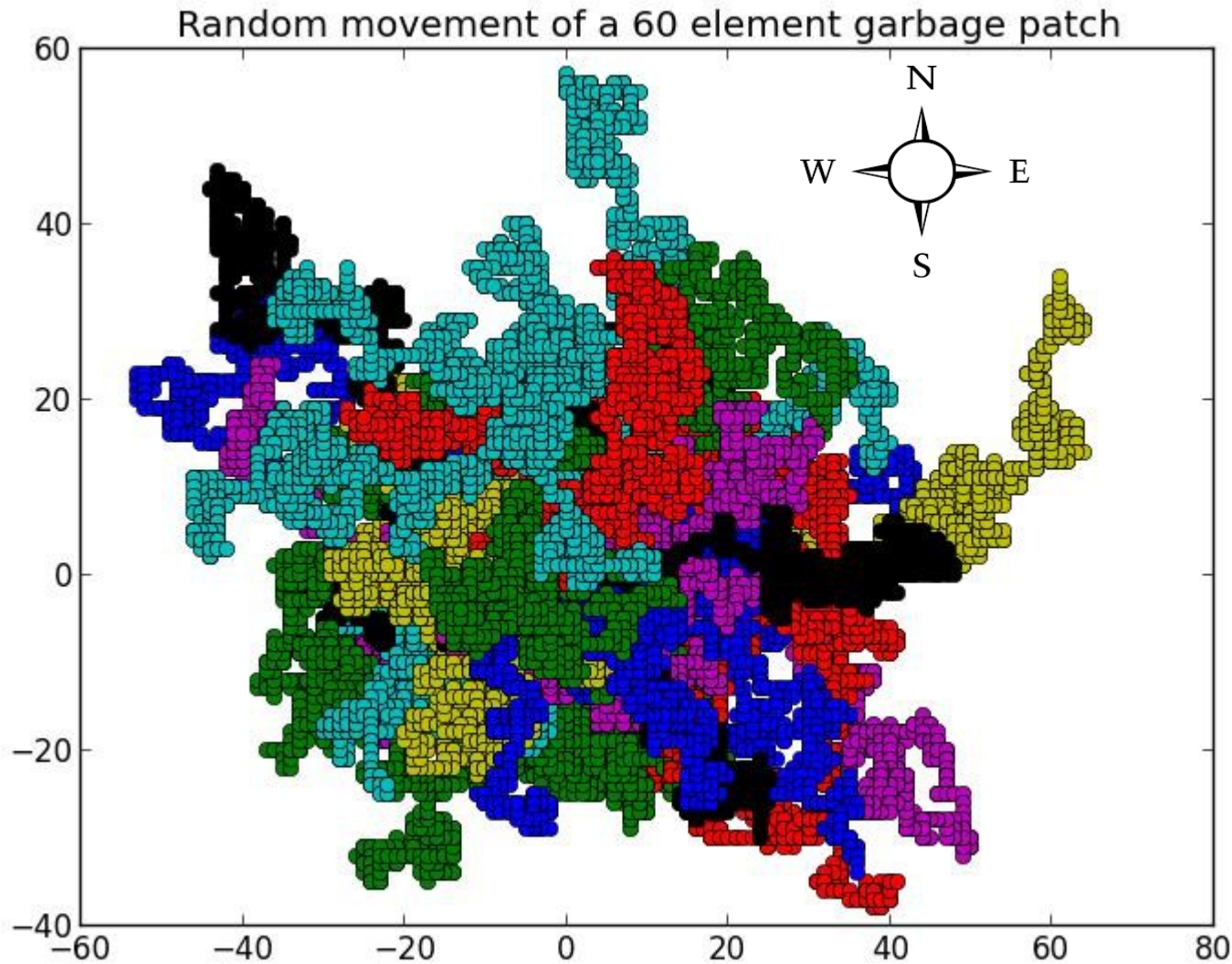
# Create trash for a garbage patch
garbagePatch = []
for k in range(60):
    garbagePatch += [Garbage()]

# time interval
maxTime = 1000
tRange = range(maxTime)

# plot the location of the trash as it randomly floats
for garbage in garbagePatch:
    x,y = [],[]
    for t in tRange:
        garbage.float()
        x += [trash.x]
        y += [trash.y]
    plt.plot(x,y,"o")

plt.savefig("garbagePatch.jpg")
plt.show()
```

# Floating Garbage



<http://hadron.physics.fsu.edu/~eugenio/comphy/examples/garbagepatch.py>

# A Root Finding Object

```
class Newton:
    """
    Root finding method using Newton's method
     $x = x_{old} + f(x) / df(x)/dx$ 
    """

    def __init__(self, f, dfdx, precision=0.1):
        """
        Constructor needs functions for f(x) & df(x)/dx
        """
        self.f, self.dfdx = f, dfdx
        self.precision = precision

    def getRoot(self, x ):
        """
        Root finding method using Newton's method
        """

        lastX, count = float("inf"), 0
        while (x - lastX)**2 > self.precision**2:
            lastX = x
            count += 1
            x = lastX - self.f(lastX)/self.dfdx(lastX)
        return [x, count]
```



# Using the Root Finding Object

create object `rto` from the class `Newton` defined in module `findroot`

```
rto = findroot.Newton(P, dPdx)
```

```
rto.precision = 1e-10      # set root finding precision
```

```
findRoots = True
```

```
while findRoots:
```

```
    guess = raw_input("Enter starting guess for root['q' to quite]: ")
```

```
    if guess != 'q' and guess != '':
```

```
        guess = float(guess)
```

```
        print( "guess: ", guess , "root:", rto.getRoot(guess)[0], sep='\t' )
```

```
    else:
```

```
        findRoots = False
```

```
        print("bye")
```

Have the object find a root and print  
the root value ignoring number of iteration steps

**Let's get working**