Spin	Linear	Transforma	tion $L$	Antilinear Transformation $A$										
	$b_i$ -	$\longrightarrow b'_i = L_{ij}$	$b_j$	$b_i \longrightarrow b'_i = A_{ij}b^*_j$										
Observable	$\widetilde{\Gamma}_4$	$\widetilde{\Gamma}_{10}$	$\widetilde{\Gamma}_{12}$	$\widetilde{\Gamma}_6$	$\widetilde{\Gamma}_8$	$\widetilde{\Gamma}_{13}$	$\widetilde{\Gamma}_{15}$							
$\sigma(\theta)$	+	+	+	+	+	+	+							
Σ	+	+	+	+	+	+	+							
T	+	+	+	+	+	+	+							
Р	+	+	+	+	+	+	+							
G	-	-	+	+	-	+	-							
Н	-	_	+	-	+	-	+							
E	-	-	+	-	+	-	+							
F		-	+	+	-	+	-							
$O_x$		+	_			+	+							
$O_z$	_	+	_	+	+	·	_							
$C_x$	-	+	-	+	+	-	-							
$C_z$		+	_	-	-	+	+							
$T_x$	+	_	_	+	_	_	+							
$T_z$	+	-	-	-	+	+	-							
$L_x$	+	_	_	_	+	+	_							
$L_z$	+	-	-	+	-	-	+							

Suppose we measure 7
observables that shown
in red boxes (4S + G,F,O\_x).

This observables are not invariant under L transformations (columns 1 to 3) (see red boxes, the signs become negative). So far so good.

However, there exists one antilinear transformation under which the 7 observables remain invariant. That's shown in col. 6. Then we need one more observable that changes under this transformation.
Observables shown in blue boxes change sign, hence they are the possible choices for the 8<sup>th</sup> observable. They are -

 $_{TR}$  (O\_z, C\_x, T\_x and L\_z).

This table shows the possible candidates for the 8<sup>th</sup> observable (shown as circles), given 3 initially selected double-spin measurements (shown as X) on top of the 4 S types.

For the initial measurements (4S + G,F,Ox), the possible candidates are (C\_x, T\_x and L\_z), consistent with the my prediction on previous slide (except for  $O_z$ )

G	x	х	х	х	х	х	х	x	х	х	х	х	х	х	х	х	$\mathbf{x}$	х	х	х	х	х	х	x	
H	х	$\mathbf{X}$																	$\mathcal{BT}$						
E									$\mathbf{X}$																
F																	х	$\mathbf{x}$	х	$\mathbf{X}$	$\mathbf{X}$	$\mathbf{X}$	$\mathbf{X}$	$\mathbf{X}$	
$O_x$	$\mathbf{x}$		0		0	0	Ο	0	х	0	0	0	0	0	0	0	х		Ο		0			0	
$O_z$		$\mathbf{X}$		Ο	Ο	0	0	0	0	$\mathbf{X}$	Ο	Ο	0	0	Ο	0		$\mathbf{x}$		0		0	0		$\mathcal{BR}$
$C_x$	0		$\mathbf{X}$		ο	ο	0	0	0	Ο	$\mathbf{X}$	ο	ο	Ο	Ο	0	0		$\mathbf{X}$			Ο	Ο		
$C_z$		ο		$\mathbf{X}$	ο	ο	ο	0	0	Ο	ο	$\mathbf{X}$	ο	ο	ο	0		о		$\mathbf{X}$	ο			0	
$T_x$	0	0	Ο	Ο	х	0	Ο	0	0	0	Ο	0	$\mathbf{X}$		0		0			Ο	х		0		
$T_z$	0	Ο	Ο	Ο	Ο	$\mathbf{X}$	Ο	0	0	Ο	Ο	Ο		$\mathbf{X}$		0		о	Ο			$\mathbf{X}$		0	$T\mathcal{R}$
$L_x$	0	Ο	ο	Ο	Ο	ο	$\mathbf{X}$	0	0	Ο	Ο	ο	Ο		$\mathbf{X}$			о	Ο		Ο		$\mathbf{X}$		
$L_z$	0	Ο	Ο	Ο	Ο	Ο	Ο	х	0	0	Ο	ο		Ο		x	0			Ο		Ο		x	